



1  
00:00:07,550 --> 00:00:06,170  
my name is jessica i am i am from

2  
00:00:09,259 --> 00:00:07,560  
polytechnic institute of new york

3  
00:00:12,080 --> 00:00:09,269  
university is located in brooklyn new

4  
00:00:13,190 --> 00:00:12,090  
york i am part of the mei group which is

5  
00:00:15,709 --> 00:00:13,200  
stand for is minority education

6  
00:00:18,529 --> 00:00:15,719  
initiative program I'm work in the

7  
00:00:20,720 --> 00:00:18,539  
section 347 the robotics mobility

8  
00:00:22,550 --> 00:00:20,730  
program lab do i do work is the the

9  
00:00:24,410 --> 00:00:22,560  
clarity software development lab I'm

10  
00:00:28,070 --> 00:00:24,420  
currently interning with my mentor

11  
00:00:30,710 --> 00:00:28,080  
Richard Petrus and dr. Tara esslyn what

12  
00:00:32,510 --> 00:00:30,720  
they wanted was to be able to plot rover

13  
00:00:35,299 --> 00:00:32,520

trajectories like in a visual

14

00:00:37,520 --> 00:00:35,309

presentation format and the best way

15

00:00:38,930 --> 00:00:37,530

that he thought would be is to go

16

00:00:41,030 --> 00:00:38,940

through google earth why is this

17

00:00:43,280 --> 00:00:41,040

important you can use this program to

18

00:00:45,319 --> 00:00:43,290

make your analysis of anything that has

19

00:00:46,910 --> 00:00:45,329

coordinate sensitive information for

20

00:00:48,500 --> 00:00:46,920

instance you can determine where to

21

00:00:51,229 --> 00:00:48,510

Rover with was its trajectory

22

00:00:52,970 --> 00:00:51,239

predictable it was it precise obviously

23

00:00:54,380 --> 00:00:52,980

it's good for visual representation if

24

00:00:55,819 --> 00:00:54,390

you want to use this in meetings that

25

00:00:58,490 --> 00:00:55,829

you're having to see how your progress

26

00:01:01,069 --> 00:00:58,500

is going or to show the public of what

27

00:01:03,410 --> 00:01:01,079

you've accomplished so far at school I'm

28

00:01:04,939 --> 00:01:03,420

into providing some studying Computer

29

00:01:06,469 --> 00:01:04,949

Engineering which is half computer

30

00:01:08,870 --> 00:01:06,479

science programming and half electrical

31

00:01:10,310 --> 00:01:08,880

engineering so if you take the tooling

32

00:01:12,109 --> 00:01:10,320

together the programming with the

33

00:01:14,289 --> 00:01:12,119

hardware and software in a way you kind

34

00:01:16,760 --> 00:01:14,299

of get a robot I want to work with

35

00:01:18,590 --> 00:01:16,770

prosthetics robotic prosthetics when

36

00:01:21,020 --> 00:01:18,600

people who are missing limbs and things

37

00:01:23,870 --> 00:01:21,030

like that even get more in depth with

38

00:01:26,719 --> 00:01:23,880

nano technology and medicine delivery

39

00:01:29,929 --> 00:01:26,729

having JPL my resume I I think for me is

40

00:01:31,969 --> 00:01:29,939

a huge huge deal it's a great very great

41

00:01:34,850 --> 00:01:31,979

environment you have all your resources

42

00:01:37,130 --> 00:01:34,860

here available to you the people they're

43

00:01:39,050 --> 00:01:37,140

very friendly they want to help you if